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1. SUBJECT

1.1 This document provides the minimum requirements to be followed by CONTRACTOR regarding design, manufacturing of structures and installation of the Environmental Data Acquisition System (ENV System) to be used in Floating, Production Storage and Offloading (FPSO) platforms deployed in Brazilian offshore basins. The abbreviation ENV refers to the word "Environmental".

2. ABBREVIATIONS

CCR	Central Control Room
IEC	International Electro-Technical Commission
NMEA	National Marine Electronics Association
OCEANOP	Meteorological-Oceanographic Data Collection Operational System
POS	Positioning Reference Systems for DP Shuttle Tanker Operations
UCD	Data Collection Unit
EPTA	Telecommunication Services and Air Traffic Stations
HMS	Helideck Monitoring System
ENV	Environmental Data Acquisition System
DADAS	DADAS - Environmental Monitoring Software
FAT	Factory Acceptance Test
UPS	Uninterruptible Power Supply
UPS	Uninterruptible Power Supply
FPSO	Floating, Production Storage and Offloading
FPSO	Floating, Production Storage and Offloading

3. REFERENCE DOCUMENTS, CODES AND STANDARDS

- 3.1 The installation and the equipment shall comply with rules and recommendations of the classification society, as well as following technical standards in their latest versions.
 - a. IEC-60079 Electrical Devices for Explosive Gaseous Atmospheres;
 - b. NMEA 0183 Standard for Maritime interface between electronic devices;
 - c. ICA 63-10: Estações Prestadoras de Serviços de Telecomunicações e de Tráfego Aéreo – EPTA;
 - d. MCA 101-1: Instalação de Estações Meteorológicas de Superfície e de Altitude;
 - e. NORMAM-27: Normas da autoridade marítima para homologação de helideques instalados em embarcações e em plataformas marítimas.
- 3.2 Brazilian Standards
 - a. Portaria INMETRO nº 115 (21/março/2022): Regulamento de avaliação da conformidade de equipamentos elétricos para atmosferas potencialmente explosivas, nas condições de gases e vapores inflamáveis e poeiras combustíveis.
 - b. NR-10: Segurança em instalações e serviços em eletricidade
 - c. NR-37: segurança e saúde em plataformas de petróleo
 - d. ANATEL: Resolutions from Agência Nacional de Telecomunicações.

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4. GENERAL REQUIREMENTS

- 4.1 For PETROBRAS detailed design requirements for Installation, Configuration, Tests training and commissioning CONTRACTOR shall comply with the Technical Specification I-MD-3010.00-5510-760-PPT-001 – GENERAL CRITERIA FOR TELECOMMUNICATIONS DESIGN.
- 4.2 For telecommunications symbols, the Detailed Design shall comply with the Technical Specification: I-ET-3000.00-0000-940-P4X-002 SYMBOLS FOR PRODUCTION UNITS DESIGN.
- 4.3 For telecommunications TAGs, the Detailed Design shall comply with the Technical Specification: I-ET-3000.00-1200-940-P4X-001 TAGGING PROCEDURE FOR PRODUCTION UNITS DESIGN.
- 4.4 All electrical requirements for telecom package shall be in accordance with I-ET-3010.00-5140-700-P4X-003 – ELETRICAL REQUIREMENTS FOR PACKAGES FOR OFFSHORE, I-ET-3010.00-5140-700-P4X-001 - SPECIFICATION FOR ELECTRICAL DESIGN FOR OFFSHORE UNITS, I-DE-3010.00-5140-700-P4X-003 - GROUNDING INSTALLATION TYPICAL DETAILS and I-ET-3010.00-5140-700-P4X-005 - REQUIREMENTS FOR HUMAN ENGINEERING DESIGN FOR ELECTRICAL SYSTEMS OF OFFSHORE UNITS.
- 4.5 All systems shall be installed in appropriated rack in the Telecommunication Upper Room of the Accommodation Module.
- 4.6 The Environmental Data Acquisition System monitors and computers shall be installed inside the CCR Central Control Room and Radio Room.
- 4.7 All details of designs, materials, structures, installation (including communication wiring and the installation of junction boxes, assemblies, documentations, tests and commissioning are included in the CONTRACTOR's scope of deliveries, unless when specified otherwise herein. Moreover, the elaboration of a schedule for the delivery of designs, technical drawings, installation and commissioning reports and reports on test procedures are under the CONTRACTOR's responsibility. All documents are to be submitted for the PETROBRAS' approval.
- 4.8 The ENV System shall be designed, manufactured, tested and certified according to the Rules of the Classification Society, when applicable. The commissioning and functional tests shall be done by the supplier.
- 4.9 PETROBRAS shall approval the detailed design for validation the locations for installation of sensors.
- 4.10 CONTRACTOR shall also provide any explanations requested by PETROBRAS.
- 4.11 Upon commissioning, the ENV System shall be a Data Collection Unite (or Unidade de Coleta de dados, UCD in Portuguese) for PETROBRAS' Meteorological-Oceanographic Data Collection Operational System (OCEANOP) operating in several exploration and production units. The UCD sensors, the data collection methods and the data acquisition and processing software shall be standardized in order to operate with the OCEANOP System.

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<i>PETROBRAS</i> 4.12 Any m			м	INTERNAL			
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 4.12 Any modifications in this specification regarding the model or manufacture of any equipment or structure and the lack of parts of the system shall be submitted for the PETROBRAS' approval. 5. SYSTEM DEFINITIONS 							
5.1		Petrobras oil production unit has an ENV					
	a dat qualif Qualif	orological and oceanographic sensors called UCD tabase and goes through an automatic qualific fication is also carried out by a team of oceanograp fied data is stored in a database and made availa e company in near real time.	ation syst ohers and	em. A manua meteorologista	al s.		
5.2	Telec	orological sensors are part of the EPTA communications and Air Traffic Services catego deck Monitoring System), which also has a motion	ory M) an				
5.3	5.3 Meteo-oceanographic data is used for planning and monitoring of vessel operations, consulting for accident investigation, underwater operations planning (diving and equipment installation), engineering projects, contingency cases (man overboard and oil spill), among others.						
5.4	5.4 Some production units, according to the rules of the field bidding, have a requirement to monitor environmental data for the Operating License with the Brazilian environmental agency (IBAMA).						
6. T	ECHN	IICAL REQUIREMENTS					
6.1	(wind humic	ENV System shall measure, present, store and tra I intensity and direction, air temperature, atmosph dity of air) and oceanographic data (intensity and nt, direction and period of waves) to other systems	eric pressu direction d	ure and relativ	/e		
6.2	meter	on sea currents shall be measured by acoustic p rs and the meteorological data shall be measur orological station.					
6.3	softwa	TRACTOR shall be responsible for the acquisition rare that will be responsible for integrate nographic sensors information.					
6.4	auton senso	system works without the intervention of ar natically after power outages. The oceanogra ors shall be controlled solely by DADAS, whereas ional software shall not be accepted.	phic and	meteorologica	al		
6.5	The I	ENV System shall receive the navigation data	(from GN	SS and AHR	S		

The ENV System shall receive the havigation data (from GINSS and AHRS ງ.ວ sensors) of the Positioning and navigation System and of the gyroscope system,

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which	aball be used for supply an institution of time	and how angle	OI/CS
	shall be used for synchronization of time ation regarding the direction of meteorolo		
	ata collected shall be processed and p d displays. The data shall also be availa	-	
headqu	ta also shall be transmitted through PETF uarter of the OCEANOP System onshore ation to several of PETROBRAS' applicat	in order to qualify	
standa system radio	MS and EPTA Class "M" standards are ind rds are covered in the ICA 63-10 and NC replication in the radio room, with approp operator, shall be configured to displa ation only.	DRMAM-27 regula priated access in t	ations. The ENV he screen to the
and pr helided	elideck Monitoring System – HMS shall I ovide wind speed (direction, intensity a ck movements in real-time, data storage, r to assist in the safety of air operations.	nd gusts), ambie	ent temperature,
possib shall b	otion sensors shall be positioned on the le, the values presented for pitch, roll, h e corrected for the height and position of ind sensors shall be installed, mandatorily	eave, heave rate the helideck, whil	e and inclination e thermometers
compu	RACTOR shall be responsible for the ter of the meteorological and oceanogran nents, as well all other materials betweer	aphic sensors of	their electronic
	ck status light is an alert visual system a f conditions that may be dangerous to the		
AAFD	elideck status light consists of a red ligh limit line, there may be, also, in other lo in any direction of approach of the aircraf	cations of the UN	
conditi	atus light when turned on will mean that ons for aircraft operation. When the statu condition to operate on that helideck.		
6.15 The st condition	atus light shall be activated manually ons:	by the Radio (Operator in the
	hen the parameters required in the HMS DRMAN-27, or	S exceed the lim	its stipulated by
b. Fr	om the Fire and Gas panel when the plat	form is in emerge	ency situation.
	RACTOR shall be responsible for all mat tion of wiring, over-water and underwate		

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cables, interfaces, racks, steel cables, switchboards, cages, crane, ballasts, connectors, adaptors, junction boxes, foundations, structures, clamps and supports for fixating the sensors, sensor handling and recovery devices, tools, installation accessories, paints, ropes and any other necessary items.

- 6.17 The manuals of the sensors shall be followed, especially regarding the assembly inclination angle (minimum inclination is preferable) and rotation.
- 6.18 CONTRACTOR shall use the 3D simulation software for locations of the installation sensors and the interaction of the underwater bundles of the current profiler with the underwater structures of the unit.
- 6.19 The ENV system shall be powered by the FPSO UPS in 220 VAC/60 Hz and other voltages (12 VDC and 24 VDC) to power the equipment and sensors, shall be obtained internally in the package with the use of rectifiers.
- 6.20 The manufacturing and the installation of the ENV System structures under the responsibility of CONTRACTOR shall be done in such a way as to facilitate maintenance and make it safe and effective. Means for recovering the sensors for cleaning and maintenance shall be made available in proper work platform and with safe devices for handling and lifting equipment.
- 6.21 As per required by I-ET-3010.00-1351-140-P4X-002 DIGITAL TWIN FOR HULL STRUCTURAL INTEGRITY MANAGEMENT, information from Metocean System shall be forwarded by LAN to HSHMS System.

7. SCOPE OF SUPPLY

- 7.1 The meteorological sensors shall be part of a "Estação Prestadora de Serviços de Telecomunicações e Tráfego Aéreo (EPTA) categoria M" which is regulated by ICA 63-10.
- 7.2 CONTRACTOR shall follow the regulations of the Brazilian Air Force for the EPTA installation and operation.
- 7.3 The sensors installation site shall be in accordance with MCA 101-1.
- 7.4 After installing the meteorological sensors, CONTRACTOR must provide the linear offset measurements for each sensor.

7.5 WIND INTENSITY AND DIRECTION

7.5.1. CONTRACTOR shall supply four wind sensors. Two shall be installed at the highest point near the helideck, other at the highest point at the bow of the FPSO and another stand in spare. The wind sensor is not restricted by its make and model. It shall have the following specification or greater precision

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dire dire	te a measuring range from 0 to 60 m.s-1 for intensity ar ection; the accuracy of 0.3 m.s-1 or 1% of reading for spection; and the temperature limit of its operation is plausible v operature where the FPSO will operate.	peed and 3° fo
You the	a reference PETROBRAS uses Anemometer 05106 Marin ung with line driver and current loop outlet, installed at the h helideck. At the bow of the FPSO uses RM Young 05501 L n intrinsically safe version, suitable for use in hazardous are	ighest point nea M Model, whicl
whi as a are tow any	callation note: The sensors shall be installed in two different ch shall be totally free of any interference for the circulation antenna radars, towers, buildings, stairs, chimneys or flares. the highest points in the units, which are generally the tele ers. Even when on such towers, the anemometers shall be other structure, such as windsocks. Poles can be fixated is anemometers.	of the wind such The best place communication installed above
be t axis sup	order to facilitate the maintenance of the anemometers, the s telescopic and have a mechanism so that it does not rotate s. CONTRACTOR shall indicate the direction of the u porting the anemometer in order to facilitate the heading of t intenance.	e around its own nit on the pole
	this sensor, CONTRACTOR needs to supply the gyroscop the computer to correct the information measured data.	be system signa
7.5.7. The	e spare anemometer shall be for use in hazardous areas, if	necessary.
	ATIVE HUMIDITY AND TEMPERATURE PROBE AND SSURE SENSOR	BAROMETRI
the	NTRACTOR shall acquire two sensors from each, one shall other shall stand in spare. The sensors are not restricted del. It shall have the following specification or greater precis	by its make and
shie 50°	e relative humidity and temperature probe shall be installe eld. Take a measuring range from 0 to 100% to relative hu C to temperature; Have accuracy of 1% of reading for relat 9,3°C for temperature.	midity and -10 to
mea tem	e barometric pressure sensor shall be installed with press asuring range from 500 to 1100 hPa; with accuracy of 0 operature limit of its operation is plausible with the expec- ere the FPSO will operate.	.3 hPa; and the
R.M	a reference, PETROBRAS uses relative humidity and temp I. Young model 41382LC with a "radiation shield" model 410	03P or VAISAL

model HMP155 with a "radiation shield" model DTR503 and barometric pressure

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sensor of R.M. Young model 61402L with pressure port model 61002 and weather-proof box model 61360.

7.6.5. Installation note: These sensors shall be installed far from heat sources such as air vents and exhausts, and in place of free atmospheric circulation. They shall be installed in accordance with premises in MCA 101-1.

7.7 WEATHER DISPLAY

7.7.1. Weather display should connect the sensors to the computer. The weather display shall show and transmit weather data through two serial ports in the format below.

II.I DDD II.I DDD II.I DDD TT.T UUU PPPP.P, where:

II.I: wind intensity (in m.s⁻¹)

DDD: wind direction (in degrees)

TT.T: air temperature (in °C)

UUU: relative humidity (in %)

PPPP.P: atmospheric pressure (in mb)

- 7.7.2. As a reference, PETROBRAS uses R. M. Young model 26800H Programmable Translator, interconnection cables and line filters.
- 7.7.3. Installation note: preferably, weather display should be installed in the rack dedicated to the ENV system. Its setting shall be in compliance with the DADAS requirements and, for these purposes. PETROBRAS can be consulted in order to provide guidance about this matter.

7.8 **OCEANOGRAPHIC SENSORS**

7.8.1. VERTICAL CURRENT PROFILER

- 7.8.1.1. CONTRACTOR shall install an Acoustic Doppler Current Profiler (ADCP) that has at least a maximum range of 1000 m. Whereas operating should profile at least 700 m.
- 7.8.1.2. The Vertical Current Profiler shall be capable of configuring the depth cell size between 16 and 20 m, velocity accuracy of 1% of measured value ± 5 mm.s-1, velocity resolution of 1 mm.s-1 and velocity range of ± 5 m.s-1.

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	WETOCEAN DATA ACQUISITION STSTEM	OI/CS	
a	This sensor is operated by DADAS server and communication and serial device server shall be in two-ways (sensor to serv sensor).		
C	There are two Vertical Current Profilers that PETROBRAS Doppler Current Profiler (ADCP) models Pinacle 45 kHz real t RD Instruments or Signature55 of Nortek.	· ·	
ti fe	The following items are included: maintenance kit, operansducer serial outlet and control cable of the ENV system wor underwater extensions at the tip of the transducer, a protection cable, spare parts and the software of sensor	vith a connection ower cable, an	
b s	nstallation Notes: Instrumentation places with obstacles oundles and side lobes of the current profilers should be avoid structure of the sensors shall be constructed and positioned so his type of obstacle.	led. The support	
7.8.2. CU	JRRENT METER		
r	CONTRACTOR shall install a Current Meter that has accur nm.s-1 to velocity and 2° to direction; range of 0 to 5 m.s-1 t o 360° to direction.	•	
7.8.2.2. A	7.8.2.2. As a reference, PETROBRAS uses the Aquadopp Mooring of Nortek.		
C	This sensor is operated by DADAS server and communi Current Meter and serial device server shall be in two-ways (and server to sensor).		
	nstallation notes: Current meter shall be installed in the sa current profiler.	me cage as the	
7.8.3. W	AVE SENSOR		
p	CONTRACTOR shall install an equipment to evaluate the period and height. In order to better quantify the wave measequipment needs to remove the FPSO movements from the mas range of 0 to 30 m to height, 3 to 30 s to period and 0 to 3	asurements, the data. Wave data	
r	The equipment shall be installed following the guidelines es manufacturer, especially in relation to the recommended hei sea level and the free area of structures around the sensor.		
	The equipment module, installed externally, shall be controll DADAS software.	ed solely by the	

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ļ	7004 hp	stallation Notes: installation sho	uld be as recommended i	OI/CS			
	manual. Preferably, in order to facilitate of maintenance, they should be installed for easy access to your modules.						
	7.8.4. ATT	TITUDE SENSOR					
	the un	ONTRACTOR shall follow Brazil e attitude sensor according to N nder the helideck center or as clo displayed referenced to the helio	NORMAM-27. The sensor solves as possible provided the	shall be installed			
	7.8.4.2. The sensor shall have at least three accelerometers assembled orthogonally. It shall have the following specifications or better:						
		Attitude – accuracy and precision 0° and 3.5° for pitch and roll ang	·	, ,			
	b. Heave – accuracy and precision of \pm 0.1 meters. Range of at least \pm 10 meters.						
	c. Average heave rate – accuracy and precision of 0.1 m.s ⁻¹ RMS (Root Mean Square) between 0 and 1.3 m.s ⁻¹ .						
		ne sensor shall have the protecti onnector.	ion class IP66 or upper of i	ts enclosure and			
	an	fter installing the attitude sensond angular offset measurement esigned of the FPSO and the cer	nts of this sensor, the g				
	7.9 COMP I	UTERS AND RACK					
	7.9.1. CON	MPUTERS					
	ex PE PE	shall be supplied and installed 0 cclusive use of the ENV System. ETROBRAS image installed by F ETROBRAS network and be us ystem.	These computers shall rece PETROBRAS and shall be	eive the standard connected to the			
	7.9.1.2. (0)	2) two industrial computers shal	I have the minimum require	ements below:			
	a.	Processor: Clock of 3 GHz or 64 bits	high				

Shall support virtualization technology

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b.	Memory:	16 GB or high			
		Standard DDR4 or high			
		Frequency 2100 MHz or high			
C.	Hard disk:	1TB			
		Interface SATA			
d.	Watchdog C	ard			
e.	04 USB v3.0) ports or high			
f.	03 Ethernet	ports (10/100/1000baseT)			
g.	Video card v	vith PCI Express X16 with 02 GB RAM (minin	าum)		
h.	h. Operational system: Windows 10 Professional 64 bit or higher, license in Portuguese.				
i.	Keyboard wi	th built-in mouse for 19" rack			
j.	Industrial LC higher	CD monitor for assembly on 19" rack, resoluti	on 1280x1024 or		
ut	ograde requir	R is responsible for any Windows versio ed by PETROBRAS. serial device server (MOXA NPort 5600 Serie			
		s required. The NPort shall connect all the ser			
cc st pr in	onnected me andard serial ovide the pro	RS-232 with the DB9 or RJ45 connector. COI oper converters to translate the signals to RS provide data exclusively to the computer dedi	s and AHRS via NTRACTOR shall 5-232. All sensors		
acin	1.6. CONTRACTOR shall request PETROBRAS for the sensor test procedure according to the setting accepted by DADAS. These tests can be performed in the software of the manufacturers of each sensor. The computer of the ENV System shall be connected to the Platform's UPS.				
in Et C	7.9.1.7. The industrial computers and all sensor control equipment shall be installed in a 19" rack. At PETROBRAS' discretion, new instrumentations may receive Ethernet-serial conversion modules as substitutes for the computers. CONTRACTOR shall acquire both (computer and conversion module specified by PETROBRAS).				
as th	s for their sett	R is responsible for supplying all software and ings, so as to unite the data from the ENV Sy priate format in the computer. This includes	stem and present		

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sy in C P co	ne others (02) two computers shall be standard with minim rstem Windows 10 Professional, or newer version, in Po stalled software Dadas Client; monitor 24"; keyboard ONTRACTOR is responsible for any version upgrad ETROBRAS. These computers will be installed at CCR ar onnect to PETROBRAS network and they shall follow technic I-ET-3010.00-5511-768-PPT-001 IT EQUIPMENTS.	rtuguese; to be d and mouse. e required by d Radio Room,			
U	 7.9.2.10 CONTRACTOR is responsible for any Windows version and hardware upgrade required by PETROBRAS. 7.9.2. DATA VIEWING SOFTWARE 				
ac P in w	ONTRACTOR shall provide the meteorological-oceanogra equisition and display software DADAS by A+D (www.au ETROBRAS' version. For this, a software license shall stalled in one of the industrial computer. The software shal hole system operation period. The purchased license shall ith 500 variables and 6 simultaneous Clients.	tomasjon.no) in be bought and I be kept for the			
	7.9.2.2. The system (computer + DADAS) shall be installed and the sensors acquire and store data.				
7.9.3. EN	/ SYSTEM RACK				
S	ONTRATOR shall provide and install (01) one CLOSED RAYSTEM indoor equipment installation. This rack sh pecifications below:				
	shall be closed, 19 inches standard, 42U height, minimur hm (internal dimensions) and 800 mm of useful width (interr				
U	shall have AC universal standard sockets for 19 inches standard sockets for 19 inches standard sockets shall be equipped, at least, 04 (fo dditional for PETROBRAS future use.				
c. (
	alazed door at the front: Single-pane safety glass, 3 mm inge, and security lock;	, including 130°			
h		-			

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f		OI/CS			
f.	Vertical cable organizer, for RF cables and controllers cable;				
g.	Internal light only on the rear access;				
h.	Complete earthing Kit;				
i.	Color: RAL 7035.				
	7.9.3.2. ENV SYSTEM equipment shall be connected to both Unit's UPS bus bar A and B by means of an ATS device with enough outputs outlets to power each required equipment.				
7.9.3.3.	Automatic Transfer Switch (ATS) features required:				
	a. The ATS device shall provide reliable, redundant power to equipment loads. The ATS device shall have 02 (two) in supplying power to the connected loads.				
	b. The ATS device shall have has built-in network connectiv for remote management via Web, Telnet, SNMP and SS				
	c. Input: 02 (two) inputs for two separate power sources (A	, B).			
	. Outputs: 08 (eight) outputs (minimum) to power equipment.				
	e. Transfer time: 10ms maximum.				
	. Visual singling operation mode indication by frontal LEDs.				
	g. 19" standard for rack installation.				
7.9.3.4.	The ENV computer and the weather display shall be instand and connected to the environmental sensors.	alled in the rack			
7.9.3.5.	The rack shall be installed close to the POS rack in the Telecommunication Upper Room.				
7.9.3.6.	Annex presents a diagram exemplifying the connection meteorological and oceanographic instruments, the con PETROBRAS network.				
7.10 HM	S – Helideck Monitoring System				
7.10.1.	It shall be supplied a complete HMS – Helideck Monitoring System complying with Brazilian Civil Aviation Authorities regulations.				
7.10.2.	During Hook up operation in Brazil the meteorological and attitude sensors shall be calibrated for less than 6 months.				

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7.11 Hel	ideck Status Light				
7.11.1.	It shall be supplied a complete helideck status light complyi Navy Authorities regulations (NORMAM-27).	ng with Brazilian			
8. COM	MISSIONING				
8.1 CA	BLE INTEGRITY				
	ne following tests shall be executed for all instrumentati stallation:	on cables after			
a.	Electrical continuity.				
b.	Insulation test with megohmmeter.				
8.2 ME	TEOROLOGICAL SENSORS				
a.	Wind sensor shall be properly installed with bow orientation.				
b.	b. Gyroscope sensor shall be working during the commissioning.				
C.	c. Wind direction shall be tested at 0, 90, 180 and 270 degrees.				
d.	Temperature and wind speed data shall be compared meteorological station.	d with portable			
8.3 OC	EANOGRAPHIC SENSORS				
a.	Current profiler and current meter shall be communicating w computer at RACK.	ith the industrial			
b.	Basic commands shall respond correctly.				
C.	Sensors shall be installed in the cage.				
d.	The cage shall be submerged and single ping tests shall be made.				
e.	Wave sensor shall be communicating with the industrial corproperly.	nputer and work			
8.4 CO	MPUTERS				
a.	Dadas software shall be installed and working properly.				
h	Industrial computers shall be communicating with sorial day				

b. Industrial computers shall be communicating with serial device server.

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C. /	All sensors shall be communicating with serial device server					
d. 5	Standard computers shall be working with Dadas Client and with Dadas Server.					
8.5 ATTI	TUDE SENSOR					
	a. Sensor shall be installed near the helideck and distances between sensor and helideck center provided.					
8.6 WINC	СН					
8.7 Appr	oval of commissioning					
the inst	8.7.1. CONTRACTOR shall submit the entire system specified herein to approval by the PETROBRAS, which shall evaluate the designs, the manufacturing and installation of the structures and the data collected for approval of the commissioning.					
eva	er the installation of the sensors, the data collected shall luation period of at least one month. In such period, the tinuously approved by the consistency rules of PETROBRA	e data shall be				
	8.7.3. In case of PETROBRAS does not approve the data, the issues are to be solved as soon as possible, and a new homologation process will begin.					
	9. INFRASTRUCTURE REQUIREMENTS					
9.1 Su i	rface oceanography instrumentation					
	e support and fixation structures of the oceanographic equative structed and installed according to the premises below:	ipment shall be				
	hall be provided safe ways of recovering equipment for m aning, such as proper work platforms and safety brakes for t					
	hall have handling and safety devices installed, such as an a manhole or a tilting frame for oceanographic sensors;	ı advanced floor				
9.2.3. ln p	places with the least possible vibration;					
inte	such a position that the sensors do not receive any interfere eract with parts of the unit, such as arms, columns, anchor usters, hull, etc. A 3D simulation intended for evaluation	ing lines, risers,				

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	NTRACTOR is essential in order to verify the interaction of dles of the current profiler with the underwater structures;	the underwater			
9.2.5. In conditions that allow the sensors to be at least 30 m deep and at least 8 m below the hull in order to avoid operation above water due to the action of waves and tides and to avoid any influence from parts of the platform, such as arms, anchoring lines, hull and other underwater parts of the unit. Places such as the bow and the stern are the most indicated due to the inclination of the hull;					
9.2.6. So as to minimize all movements the sensors shall be subjected, structures fixed in only one support cable shall not be acceptable, since they allow for the rotation of the sensors;					
cau	9.2.7. They shall meet the needs for prevention and protection against damages caused by hitting other structures, as well by other vessels operating near the unit;				
elec	9.2.8. The underwater electric cables shall be inserted in protective hoses or otherwise electromagnetic cables used in the cage shall be hollow and meshed so as to reduce the water carryover area;				
9.2.9. Ball	ast shall be built in rings to ease the assembly during move	ment;			
9.2.10. H	loses shall be used in order to protect the submerged cable	Э;			
e	All materials (equipment cage, ropes, cables, screws, parts, nuts, shackl etc.) provided by CONTRACTOR shall be made of stainless steel 31 except for ballasts, which may be made of other materials other th ferromagnetic materials;				
9.2.12. Technical designs shall include the installation of junction should be as close as possible of the sensor installation plahave protection and safety degrees compatible with the chara places where they are being installed;		laces, and shall			
e	The space dedicated to the winch for lifting oceanographic s established as close as possible to the location where the se installed.				
	Annex contains examples of support and frame structure of support and frame structure of the structure of th	uctures of the			
10. OFFSET MEASUREMENTS					
10.1 The linear and angular offset measurements required in this Technical Specification shall be determined by CONTRACTOR using land topographic survey.					
10.2 A topographic report must be generated with the following information:					

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	and ang	Description of the technique, methodology and equipment used for linear and angular offsets survey, as well as indices/calculations that requested accuracy has been achieved;				
	between	Drawing with vertical and horizontal offsets with decimetric tolerance between the attitude sensor, helideck center, geometric center of the FPSO, meteorological sensors and vessel draft (minimum, maximum and medium);				
	Diagram containing angular offsets with decimal degree tolerance, the attitude sensor, helideck center and the geometric center designed of the FPSO.					
11. ANNEX	ζ					
	مار مالم س					
11.1 Blo	ck diag	ram				
		•			s between the me and the PETROB	•
WIND SENSOR 3	4.20 4		Ν	IEAR THE HELID	ECK	
IN BOW	4-20 mA	WIND SENSOR 1 NEAR THE HELIDECK	WIND SENSOR 2 NEAR THE HELIDECK	TEMPER/ HUMIDITY		
Module 1 d	or 2			.0 mA		
					·	ENV REMOTE STATION RADIO ROOM
			WEATHER DISPLAY		KEYBOARD	MONITOR
ATTITUDE SENSOR	RS-422	RS-232			MOUSE	KEYBOARD
			INDUSTRIAL			MOUSE
WAVE SENSOR	RS-422		COMPUTER WITH SOFTWARE DADAS SERVER		KVM SWITCH	COMPUTER WITH DADAS CLIENT
NEAR THE HELIDECK						ENV REMOTE STATION
G	NSS SENSOR		INDUSTRIAL COMPUTER			CENTRAL CONTROL ROOM
	M POS SYSTEM	RS-232	COMPOTER			MONITOR
	HRS SENSOR M POS SYSTEM	RS-232	SERIAL DEVICE			KEYBOARD
POSIT	TIONING RACK		<u> </u>			COMPUTER
					TORING SYSTEM RACK	WITH DADAS CLIENT
			JUNCTION BOX AND WINCH		PETROBRAS	
		RS-422	RS-4	85	NETWORK	
		VERTICAL CURRE PROFILER	ENT CURRENT	METER		
			PLACE TO B			HSHMS RACK
Figure 1: Block diagram for ENV System.						
11.2 Support and frame structures of the oceanographic equipment						
11.2.1. From Petrobras' experience, the most efficient structures are such as an advanced floor with trapdoor (Figure 2) or a tilting frame (Figure 3), where the winches and the cage maintenance location are on the same deck.						

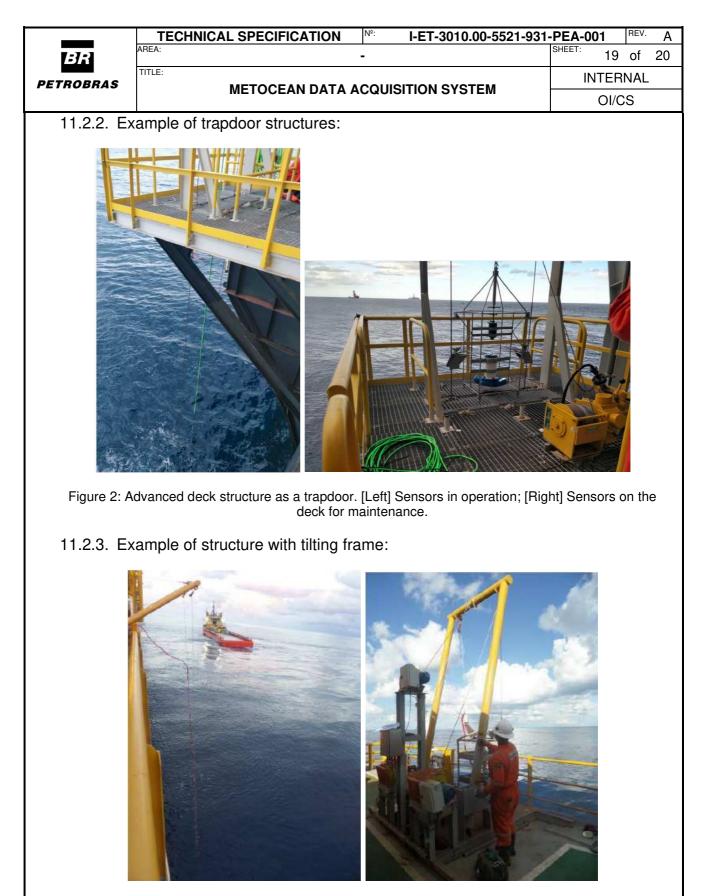


Figure 3: Structure with a-frame. [Left] Sensors in operation; [Right] Sensors on the deck for maintenance.

11.3 The equipment cage needs to be hollow and have enough ballast to avoid drag and suffer the effects of buoyancy.

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11.3.1. Example of equipment cage:

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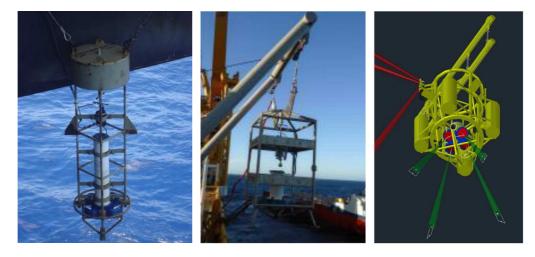


Figure 4: [left] cage model with ballast below [center] cage model with ballast integrated in the structure [right] 3D cage model showing acoustic signals propagating without obstacle.