	TECHNICAL SPECIFICATION		Nº: I-ET-3010.00-5140-712-P4X-001						
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DESIGN	ESUP	ESUP	ESUP	ESUP	EEI/ESES	EEI/ESES	EEI/ESES	EEI/ESES	
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CHECK	CAVALIERE	VRCARDOSO	THIAGO VINH	JOAOCASTRO	U4U8	U4U8	U4U8	KIE9	
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AREA:

SHEET: 2 of 19

TITLE:

**LOW-VOLTAGE INDUCTION MOTORS FOR
OFFSHORE UNITS**

INTERNAL

ESUP

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1 OBJECTIVE

This specification establishes the necessary technical requirements for design, manufacture and supply of low-voltage induction motors for offshore Units.

2 REFERENCE STANDARDS AND DOCUMENTS

2.1 GENERAL

- 2.1.1 The standards, codes and recommendations that shall be applied to motors design are listed below.
- 2.1.2 At motors design, national laws and regulations shall have priority, followed by IEC standards. Other standards shall be applied where specified by PETROBRAS.
- 2.1.3 Exceptionally, where it is clearly justifiable and approved by PETROBRAS, ANSI, NEMA, IEEE and others internationally recognized standards may be used.
- 2.1.4 All standards shall be used on their latest revisions.
- 2.1.5 Manufacturer shall provide the necessary spare parts for the commissioning and pre operation periods.

2.2 CODES, STANDARDS AND RECOMMENDED PRACTICES

2.2.1 IEC - INTERNATIONAL ELECTROTECHNICAL COMMISSION

- IEC 60034 Rotating Electrical Machines - Parts 1, 2-1, 5, 6, 7, 8, 9, 11, 12, 14, 18 and 25, 27;
- IEC 60072 Dimensions and Output Series for Rotating Electrical Machines;
- IEC 60079 Explosive Atmospheres - Parts 0, 1, 7 and 14;
- IEC 60085 Electrical Insulation - Thermal Evaluation and Designation
- IEC 61892 Mobile and Fixed Offshore Units - Electrical Installations - Parts 1 and 3;

2.2.2 IEEE - INSTITUTE OF ELECTRICAL AND ELECTRONIC ENGINEERS (only where specified)

- IEEE Std 43 Recommended Practice for Testing Insulation Resistance of Rotating Machinery.

2.2.3 NEMA - NATIONAL ELECTRICAL MANUFACTURERS ASSOCIATION (only where specified)


- MG1 Motors and Generators

2.2.4 NFPA - NATIONAL FIRE PROTECTION ASSOCIATION (only where specified)

- NFPA-20 Standard for the Installation of Stationary Pumps for Fire Protection

2.2.5 ASTM - AMERICAN SOCIETY FOR TESTING AND MATERIALS

- ASTM B26/B26M Standard Specification for Aluminium-Alloy Sand Castings
- ASTM B108/B108M Standard Specification for Aluminium-Alloy Permanent Mold Castings

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<p>ASTM B221 Standard Specification for Aluminum and Aluminum-Alloy Extruded Bars, Rods, Wire, Profiles, and Tubes</p> <p>2.2.6 ISO - INTERNATIONAL ORGANIZATION FOR STANDARDIZATION (only where specified)</p> <p>ISO 20816-1 Mechanical Vibration – Measurement and Evaluation of Machine Vibration - Part 1: General Guidelines</p> <p>2.2.7 <i>PRESIDÊNCIA DA REPÚBLICA - MINISTÉRIOS DE MINAS E ENERGIA, CIÊNCIA E TECNOLOGIA, DO DESENVOLVIMENTO, INDÚSTRIA E COMÉRCIO EXTERIOR</i> Portaria nº 1 June 29th, 2017</p> <p>2.2.8 <i>INMETRO - INSTITUTO NACIONAL DE METROLOGIA NORMALIZAÇÃO E QUALIDADE INDUSTRIAL</i> Portaria 115 March 21st, 2022 Portaria 290 July 7th, 2021</p> <p>2.2.9 ANSI - AMERICAN NATIONAL STANDARDS INSTITUTE</p> <p>ASME B 1.20.1 Pipe Threads, General Purposes (Inch)</p> <p>EASA AR100 Recommended Practice for the Repair of Rotating Electrical Apparatus</p> <p>2.2.10 IMO - INTERNATIONAL MARITIME ORGANIZATION</p> <p>IMO IA811E Code for the Construction and Equipment of Mobile Offshore Drilling Units (MODU CODE)</p> <p>2.2.11 RULES OF CLASSIFICATION SOCIETY</p> <p>2.3 BRAZILIAN LABOUR AND EMPLOYMENT MINISTRY</p> <p>NR-10 <i>Segurança em Instalações e Serviços em Eletricidade</i></p> <p>NR-12 <i>Segurança no Trabalho em Máquinas e Equipamentos</i></p> <p>NR-37 <i>Segurança e Saúde em Plataformas de Petróleo</i></p> <p>2.4 REFERENCE DOCUMENTS</p> <p>[1] DR-ENGP-I-1.15 – COLOR CODING</p> <p>[2] I-ET-3010.00-1200-956-P4X-002 - GENERAL PAINTING</p> <p>[3] I-ET-3010.00-1200-300-P4X-001 - NOISE AND VIBRATION CONTROL REQUIREMENTS</p> <p>[4] I-LI-3010.00-5140-700-P4X-001 - ELECTRICAL EQUIPMENT DATA SHEET MODELS</p> <p>[5] I-ET-3010.00-5140-700-P4X-001 - SPECIFICATION FOR ELECTRICAL DESIGN FOR OFFSHORE UNITS</p> <p>[6] I-ET-3010.00-5140-700-P4X-002 - SPECIFICATION FOR ELECTRICAL MATERIAL FOR OFFSHORE UNITS</p>			

[7] I-ET-3010.00-5140-700-P4X-009 – GENERAL REQUIREMENTS FOR ELECTRICAL MATERIAL AND EQUIPMENT FOR OFFSHORE UNITS

[8] ELECTRICAL SYSTEM DESCRIPTIVE MEMORANDUM

Note: Documents without code in the list are documents with variations according to project characteristics. Verify in project documentation list the reference for codes of these documents.

2.5 SCOPE

Included in the scope of this specification are electric motors that:

- a) are of a wire-wound a.c. squirrel cage induction type;
- b) have a rated voltage up to 1 kV;
- c) are air cooled;
- d) are for single-speed use or are converter fed.

3 GENERAL CONDITIONS

3.1 ENVIRONMENT

- 3.1.1 Induction motors and their accessories shall be suitable for storage, service and installation on severe petrochemical, marine, tropical, damp and saline environment.
- 3.1.2 It shall be considered a design ambient temperature of 45 °C, continuously. Motors installed inside engine rooms (with steam boilers) shall have design ambient temperature of 50 °C, continuously. Classification Society requirements, when more restrictive, shall be complied with.

3.2 RATING

- 3.2.1 Induction motors shall have rated power calculated, with service factor 1.0, considering the following oversizing factors applied to driven machine brake power:
 - a) 25% for motors with rated power lower than 22 kW;
 - b) 15% for motors with rated power between 22 kW and 55 kW;
 - c) 10% for motors with rated power higher than 55 kW.
- 3.2.2 Oversizing factors lower than stipulated above shall be submitted to PETROBRAS for approval.

3.3 SUPPLY

It shall not be acceptable out of date or obsolete equipment or components. Technical support and supply of replacement parts shall be guaranteed for ten (10) years.

4 CONSTRUCTIVE CHARACTERISTICS

4.1 ELECTRICAL CHARACTERISTICS

4.1.1 RATED VOLTAGE AND FREQUENCY

4.1.1.1 The induction motors following this Technical Specification shall have rated voltage up to 1 kV and rated frequency of 60 Hz.

4.1.1.2 The motors rated voltage shall be selected according to I-ET-3010.00-5140-700-P4X-001 - SPECIFICATION FOR ELECTRICAL DESIGN FOR OFFSHORE UNITS, considering the voltage levels of the electrical system indicated in the ELECTRICAL SYSTEM DESCRIPTIVE MEMORANDUM.

4.1.2 STARTING PERFORMANCE

4.1.2.1 The motor shall be designed for direct on-line start and to accelerate the connected load to running speed with 80 % of rated voltage at the motor terminals.

4.1.2.2 Unless otherwise specified in Project Documentation, motors shall have torque characteristics as stated in IEC 60034-12 for Design N.

4.1.2.3 For motors with rated power 55 kW and above with service type S1, the accelerating time (t_a) at rated voltage, when DOL (direct on-line) started, shall not exceed:

- a) 25% of the permissible locked rotor time (t_{lr}) at running temperature (hot start) and;
- b) 25% of time t_E , for Ex e motors;

- Notes:**
- Accelerating time (t_a) shall be calculated considering direct on-line start;
 - Accelerating time (t_a) shall include the driven machine coupled and loaded at expected normal service condition;
 - Running temperature means steady state operational temperature at rated load;
 - These requirements are not applicable for motors fed from VSDs and soft-starters. If bypass of soft-starter with contactor is foreseen, the requirements are applicable.
 - Accelerating time (t_a) longer than these values shall be submitted to PETROBRAS approval, including protection coordination graphics and relays' settings, proving that it is possible to provide reliable protection to the motor. These protection coordination graphics are not included in motor Manufacturer scope.

4.1.2.4 Permissible locked rotor time (t_{lr}) at rated voltage and running temperature (hot start) shall be equal to or longer than 12 s.

Note: Shorter values of specified permissible locked rotor time (t_{lr}) shall be submitted to PETROBRAS for approval.

4.1.2.5 The number of starts and intervals shall be:

- a) With the motor initially at ambient temperature (cold start), three (3) starts in succession, coasting to rest between starts;
- b) With the motor initially at running temperature (hot start), two (2) in succession, coasting to rest between starts.

4.1.2.6 All motors shall be proper for at least one start per day for the whole lifetime.

4.1.2.7 For motors with rated power 55 kW and above, unless otherwise specified in Project Documentation, the locked rotor current (I_{lr}), at rated voltage shall not exceed 6.0 times the rated current (I_r), accepting tolerances of IEC 60034-1.

Note: Unless otherwise stated in motor Project Documentation, this requirement is not applicable to converter-fed motors.

4.1.3 OPERATING PERFORMANCE

4.1.3.1 Motors shall operate satisfactorily under the following continuous conditions:

- a) Variation of $\pm 10\%$ of rated voltage, at rated frequency;
- b) Variation of $\pm 5\%$ of rated frequency at rated voltage;
- c) Combined variation of voltage and frequency of $\pm 10\%$ of the rated values (sum of absolute values), provided the frequency variation does not exceed $\pm 5\%$ of the rated frequency.

4.1.3.2 Motors shall withstand and operate satisfactorily under the following transient conditions, based on IEC 61892-3:

- a) Variation of $\pm 20\%$ of rated voltage with the maximum recovery time of 1.5 s;
- b) Variation of $\pm 10\%$ of rated frequency with the maximum recovery time of 5 s.

4.1.3.3 Within these limits, the temperature rise shall comply with requirements of IEC 60034-1.

4.1.3.4 Current stator pulsation, when driving loads such as reciprocating pumps or compressor shall not exceed 66% of rated RMS full load current for all specified loading conditions, according to NEMA MG1.

4.1.3.5 Motors for loads with intermittent service shall be rated for the adequate duty type, as defined in IEC 60034-1.

4.1.4 EFFICIENCY

The minimum acceptable efficiency for induction motors shall be as defined in Brazilian Portaria nº 1, June 29th, 2017, as shown in Table 1. These values are the minimum for standard motors and shall be confirmed by low uncertainty methods in accordance with IEC 60034-2-1, when necessary.

Table 1 - Induction Motors Minimum Efficiency

Rated Power [kW]	Induction Motors Minimum Efficiency [%]			
	Number of Poles			
	2	4	6	8
0.12	62.0	66.0	64.0	59.5
0.18	65.6	69.5	67.5	64.0
0.25	69.5	73.4	69.0	68.0
0.37	73.4	78.2	75.3	72.0
0.55	76.8	79.0	79.5	74.0
0.75	80.5	83.5 ^a	82.5	75.5
1.1	84.0	86.5 ^b	87.5 ^c	78.5
1.5	85.5	86.5	88.5 ^d	84.0
2.2	86.5	89.5 ^e	89.5 ^f	85.5
3	88.5	89.5	89.5	86.5
3.7	88.5	89.5	89.5	86.5
4.4	88.5	89.5	89.5	86.5
5.5	89.5	91.7 ^g	91.0	86.5

Rated Power [kW]	Induction Motors Minimum Efficiency [%]			
	Number of Poles			
	2	4	6	8
7.5	90.2	91.7	91.0	89.5
9.2	91.0	92.4	91.7	89.5
11	91.0	92.4	91.7	89.5
15	91.0	93.0	91.7	90.2
18.5	91.7	93.6	93.0	90.2
22	91.7	93.6	93.0	91.7
30	92.4	94.1	94.1	91.7
37	93.0	94.5	94.1	92.4
45	93.6	95.0	94.5	92.4
55	93.6	95.4	94.5	93.6
75	94.1	95.4	95.0	93.6
90	95.0	95.4	95.0	94.1
110	95.0	95.8	95.8	94.1
132	95.4	96.2	95.8	94.5
150	95.4	96.2	95.8	94.5
185	95.8	96.2	95.8	95.0
220	95.8	96.2	95.8	95.0
260	95.8	96.2	95.8	95.0
300	95.8	96.2	95.8	95.0
330	95.8	96.2	95.8	95.0
370	95.8	96.2	95.8	95.0

- Notes:
- a) For motors in frame 80, the minimum efficiency is 83 %.
 - b) For motors in frame 80, the minimum efficiency is 84 %.
 - c) For motors in frame 90, the minimum efficiency is 85.5 %.
 - d) For motors in frame 100, the minimum efficiency is 86.5 %.
 - e) For motors in frame 90, the minimum efficiency is 87.5 %.
 - f) For motors in frame 100, the minimum efficiency is 87 %.
 - g) For motors in frame 112, the minimum efficiency is 91 %.

4.2 MECHANICAL CHARACTERISTICS

4.2.1 ENCLOSURE

4.2.1.1 Motors installed in galley, laundry and accommodation rooms (dry areas) shall have minimum protection degree IP-44. Motors installed on open deck shall have minimum protection degree IP-56. All other motors shall have protection degree IP-55.

Note: Open deck is a deck that is completely exposed to the weather from above or from at least one side.

4.2.1.2 Motors and terminal boxes shall have the same protection degree.

4.2.1.3 Unless otherwise indicated on project documents, motors with horizontal shafts shall comply with International Mounting code IM B3 (according to IEC 60034-7).

4.2.1.4 The following additional characteristics shall be provided:

- a) Identification nameplates of AISI-316 stainless steel;
- b) Painting shall be in accordance with requirements of I-ET-3010.00-5140-700-P4X-009 – GENERAL REQUIREMENTS FOR ELECTRICAL MATERIAL AND EQUIPMENT FOR OFFSHORE UNITS;
- c) CANCELLED;
- d) CANCELLED;

e) CANCELLED;

f) Sealing devices (retainers, V-ring, labyrinth, etc.) between shaft and enclosure;

g) Caulking at the connection cables passage through the casing;

h) Screws, nuts, washers and all other connecting and mounting components proper to saline aggressive atmosphere;

i) Non-sparking copper-free aluminium for external fans (frame and blades). The aluminium shall be ANSI 356.0 alloy according to ASTM B26/B26M, ANSI 359.0 alloy according to ASTM B108/B108M, 6063 alloy according to ASTM B221, or 6351 alloy according to ASTM B221.

Note: Last coat colour is applicable to motor and terminal boxes. Terminal boxes in AISI 316 without painting are acceptable.

4.2.2 WINDINGS INSULATION

4.2.2.1 The windings shall be insulated according to the methods doubly impregnated by vacuum (VPI), doubly impregnated by immersion or singly impregnated by resin dripping.

4.2.2.2 The motors' insulation system shall be of Thermal Class F (155 °C), or Thermal Class higher than F, with a maximum temperature rise at full load not exceeding the limit defined to Thermal Class B (130 °C), according to IEC 60085 and IEC 60034-18.

4.2.3 COOLING SYSTEM

Motors shall be TEFC (Totally Enclosed Fan Cooled – according to NEMA MG1) cooling type, independent of area classification and they shall comply with the cooling method IC411 defined in IEC 60034-6.

4.2.4 MOTION AND INCLINATION LIMITS REQUIREMENTS

For floating units, motors shall operate normally within motion and inclination limits (static and dynamic) specified in IMO MODU CODE, IEC 61892 series and Classification Society rules.

4.2.5 BALANCE

Motors shall be constructed so that, when running at any and every working speed, all revolving parts are well balanced.

4.2.6 VIBRATION

Motors shall comply with the requirements of IEC 60034-14.

4.2.7 NOISE LEVEL

4.2.7.1 Motors shall comply with the requirements of IEC 60034-9, and I-ET-3010.00-1200-300-P4X-001 - NOISE AND VIBRATION CONTROL REQUIREMENTS. The strictest requirement shall prevail.

4.2.7.2 Bent fan blades shall be used in the motor to achieve the noise limit, if not possible with straight fan blades.

4.2.8 BEARINGS

4.2.8.1 All motors with rated power up to 150 kW shall have ball or roller bearings. Motors with rated power over 150 kW may have ball, roller or sleeve type bearings, according to

manufacturer standard. Bearings shall have a minimum lifetime of 25,000 hours, under rated load conditions.

4.2.8.2 Motors with frame number 160 and above, as defined by IEC 60072-1, shall have bearings fitted with a greasing fitting and automatic bleeder device.

4.2.8.3 Bearings shall be fitted with sealing device, in order to avoid grease leakage or penetration of water and humidity.

4.2.8.4 Vertical motors shall have bearings designed to withstand axial stress imposed by the driven machine.

4.2.9 LUBRICATION

4.2.9.1 Ball or roller bearings shall be lubricated with grease. In this case, they shall be lubricated at the factory, in order to avoid necessity of lubrication before operation starts.

4.2.9.2 Sleeve bearings may be fitted with a self-lubrication system.

4.2.9.3 Motors with sleeve bearings shall have a sight glass indicator for oil level.

4.2.9.4 When ring lubrication is used, the rings shall be so constrained that they cannot leave the shaft.

4.2.9.5 Motors with oil lubrication shall have means to avoid liquid or gaseous oil to penetrate the motor windings.

4.2.10 TERMINAL BOXES

4.2.10.1 For motors with horizontal shaft, the Terminal Box shall be fitted to the casing, on the left side, considering the motor viewed from the D-end, with the feet at 6 o'clock and the Terminal Box at 9 o'clock (designation L according to IEC 60034-7).

4.2.10.2 Cable entry shall be from bottom side. It shall be possible to install the Terminal Box on any of the four positions (from 90° to 90°), around its own axis, allowing adjustment for cable entry from top, bottom, front or rear side.

4.2.10.3 If single-core cables are used, the removable plate and the cable glands shall be of non-magnetic material to avoid magnetic induction.

4.2.10.4 The internal available volume shall be enough to safe installation and connection of power, heating and control (or signal) cables and terminals.

4.2.10.5 There shall be separate holes for power, heating and control (or sensor) cables.

4.2.11 GROUNDING CONNECTORS AND BONDING CABLES

4.2.11.1 Motor frames shall have one grounding connector fitted on their base, outside the Terminal Box, at the same side of the Terminal Box and indelible marked with the grounding symbol.

4.2.11.2 Motors fed from VSD shall have one additional grounding connector inside the Terminal Box, indelibly marked with grounding symbol.

4.2.11.3 Bonding cables and grounding connectors cross sections shall be according to I-ET-3010.00-5140-700-P4X-001 - SPECIFICATION FOR ELECTRICAL DESIGN FOR OFFSHORE UNITS.

4.2.11.4 Bonding cables shall be according to I-ET-3010.00-5140-700-P4X-002 - SPECIFICATION FOR ELECTRICAL MATERIAL FOR OFFSHORE UNITS.

4.2.12 TERMINALS

4.2.12.1 Unless otherwise specified in Project Documentation, motors shall be furnished with three or six power terminals, marked according to IEC 60034-8. Motors shall have an information plate in stainless steel AISI 316 showing the connection possibilities and the corresponding voltages.

4.2.12.2 For grounding terminals see item 4.2.11.

4.2.12.3 All motor cables (power and control) shall be indelibly marked inside the terminal boxes.

4.2.12.4 Soldered terminals shall not be used. Terminals insulating supports shall be of non-hygroscopic and non-combustible materials.

4.2.12.5 Control terminal blocks shall be of the indirect pressure screw type.

4.3 ACCESSORIES

4.3.1 LIFTING EYELETS

All motors with weight above 25 kgf shall be fitted with lifting eyelets.

4.3.2 HEATING RESISTORS

4.3.2.1 The following motors shall have internal heating resistors:

- all motors with rated power equal to or bigger than 22 kW;
- all motors installed in humid areas (e.g. pontoon pump room, main deck, and spider-deck);
- all motors installed outdoors;
- all essential motors (fed from essential switchgear or MCC).

4.3.2.2 The heating resistors shall be shielded type, with rated voltage 220 VAC for each individual resistor used. The resistors shall be suitable to 220 VAC 2ph ungrounded power supply.

4.3.2.3 The maximum internal temperature when heating resistors are turned on shall not cause any damage to winding or insulating parts.

4.3.2.4 For motors certified for installation in hazardous areas, the temperature at surfaces with heater turned on and environmental temperature of 45 °C shall not exceed the limits defined by IEC 60079.

4.3.2.5 A warning plate shall be located next to the Terminal Box with the label:

ATENÇÃO!
AQUECEDOR LIGADO EM 220VCA.

4.3.3 WINDING TEMPERATURE DETECTORS

4.3.3.1 Single-speed motors with rated power 150 kW and above shall have two three-wire Pt-100 platinum resistance temperature sensors (RTDs) per phase for temperature detection.

4.3.3.2 All converted-fed motors shall have two three-wire Pt-100 platinum resistance temperature sensors (RTDs) per phase for temperature detection.

4.3.3.3 Winding temperature detectors shall comply with IEC 60751.

4.3.4 BEARING TEMPERATURE DETECTORS

4.3.4.1 Motors fitted with sleeve type bearings shall have one three-wire Pt-100 platinum resistance temperature sensor (RTD) for temperature detection complying with IEC 60751.

4.3.4.2 When temperature switches are required, they shall have single pole double through (SPDT) contacts, operating in order that, when one contact opens, the other closes simultaneously.

4.3.4.3 The measuring points shall be according to IEC 60034-1.

4.3.4.4 Bearing temperature sensors shall be connected to temperature controllers supplied by Packager and installed in a Package Panel. Package Panel shall be the Package Control Panel, in case of Packages with this kind of panel. For Packages without Package Control Panel, Package Panel shall be installed in the Package skid and shall be proper to external auxiliary voltage 220 Vdc ungrounded. Package Panel shall comply with item 4.4.2. Trip and alarm signals shall be dry contacts, available for remote actuation.

4.3.5 CABLE GLANDS

4.3.5.1 Cable glands shall be of stainless steel AISI 316.

4.3.5.2 The cable glands shall be supplied by the motor manufacturer.

4.3.5.3 The motors certified for installation in hazardous area, the cable glands must have the same type of Ex protection of the motor on which they are mounted.

4.3.5.4 Unless otherwise stated, threaded joints shall be taper type, NPT with standardized tolerances according to ASME B 1.20.1. For motors certified for installation in hazardous areas, threaded joints shall comply with requirements of IEC 60079-0.

4.3.6 IDENTIFICATION PLATES

4.3.6.1 The identification plate shall be marked according with IEC 60034-1 and the following information shall be included:

- a) PETRÓLEO BRASILEIRO S/A - PETROBRAS;
- b) PETROBRAS Unit name;
- c) Motor identification tag;
- d) PETROBRAS RM number;
- e) PETROBRAS PC number;
- f) Frame designation;
- g) Service factor;
- h) Efficiency at 100% load;
- i) Bearings identification numbers;
- j) Permissible locked rotor time (tlr);
- k) Cooling method designation;
- l) Starting torque design designation;
- m) Ratio between locked-rotor current (I_{lr}) and rated current (I_r);

n) Hazardous areas classification protection, according to IEC 60079-0, including time tE, for Ex e motors.

4.3.6.2 Motors with rated power from 0.12 kW up to 370 kW shall have an additional information plate, complying with requirements of INMETRO *Portaria* nº 290, July 7th, 2021 (ENCE – “*Etiqueta Nacional de Conservação de Energia*”). ENCE included in the main identification plate is acceptable.

4.4 ADDITIONAL REQUIREMENTS FOR MOTORS INSTALLED IN HAZARDOUS AREAS

4.4.1 Motors and electrical accessories installed in hazardous areas shall comply with IEC 60079 (all parts) and INMETRO *Portaria* nº 115, March 21st, 2022.

4.4.2 Motors and electrical accessories installed in external safe or hazardous areas, which shall be kept operating during emergency shutdown ESD-3P or ESD-3T shall be certified for installation in hazardous areas Zone 2 Group IIA temperature T3, unless they are automatically de-energized if there is gas in the equipment area, according to IEC 61892-1.

4.4.3 The kind of protection Ex and the EPL required for the motor shall be selected and specified according to requirements of IEC 60079-14.

4.4.4 Motors shall have kind of protection Ex and the EPL selected following the criteria defined in Table 2.

Table 2 - Selection of Ex Protection and EPL

Hazardous Area Classification	Zone 1	Zone 2
Type of Protection	Ex e or Ex d or Ex de	
EPL	Gb	Gc

- Notes:**
1. Type of protection Ex d shall be avoided for motors above 250 kW;
 2. Unless otherwise stated, for Zone 1 Group IIC, protection Ex e shall be selected.

4.4.5 Motors fed from VSD or soft-starters and installed in hazardous areas shall be certified as a unit association (motor-VSD-protective device, or motor-soft-starter-protective device), as required by IEC 60079-14. Alternatives foreseen in IEC 60079-14 for this certification (as a unit association) are acceptable.

4.5 ADDITIONAL REQUIREMENTS FOR MOTORS FED FROM VSD (VARIABLE SPEED DRIVES)

4.5.1 Converter-fed motors shall comply with the recommendations of IEC 60034-25.

4.5.2 CANCELLED.

4.5.3 The rated power of converter-fed motors shall be defined taking into account the additional losses due to harmonic contents and the ventilation performance for the entire frequency variation range.

4.5.4 The rated torque of converter-fed motors shall be defined taking into account the temperature rise due to additional losses and the ratio of the VSD output voltage at motor rated frequency and the motor rated voltage.

- 4.5.5 The maximum and the minimum foreseen operational speed (or frequency) shall be informed in Motor Data Sheet. Motor manufacturer shall inform the maximum and the minimum permissible speed (or frequency) and the field weakening frequency (f_0 – according to IEC 60034-25) in Motor Data Sheet.
- 4.5.6 The insulation system of converter-fed motors shall be qualified according to IEC 60034-18-41 (partial discharge free). The insulation system, including terminal box terminals, shall be suitable for IVIC C (Impulse Voltage Insulation Class) for phase-to-phase and IVIC B for phase-to-ground, according to IEC TS 60034-25.
- 4.5.7 Means shall be provided to avoid the circulation of currents between the shaft and the bearings (see IEC TS 60034-25 as reference).

4.6 PROTECTION

Manufacturers shall inform the adjustment settings for the protection functions listed in Table 3. Unless otherwise stated, the relays responsible for the protection functions shall be included in scope of supply of the manufacturer of the panel which feeds the motor.

Table 3 - Adjustment Settings to be Informed

Protection Function - Adjustment Settings to be Informed		
Nº	Description	Responsible for Information
27	Undervoltage	Motor Manufacturer
37	Undercurrent or Underpower ⁽¹⁾	Pump Manufacturer
38	Bearing High Temperature	Motor Manufacturer
46	Current Unbalance ⁽²⁾	Motor Manufacturer
48	Incomplete Sequence / Locked Rotor ⁽³⁾	Motor Manufacturer
49	Thermal Image (by Current Sensors)	Motor Manufacturer
49RTD	High Temperature (by Temperature Sensors)	Motor Manufacturer
51LR	Locked rotor	Motor Manufacturer
66	Starts/Hour & Time Between Starts	Motor Manufacturer

- Notes:**
- 1) Only for pump loads. The 37 function setting shall be based on the electric current driven at minimal permitted flow and on the maximum time at shut-off when starting. This function shall have a time delay during start condition. The manufacturer of the motor-pump assembly shall inform the minimum current value and the maximum shut-off time which the equipment supports.
 - 2) For motors above 55 kW, the manufacturer shall supply the negative sequence capability curve for the stator and rotor.
 - 3) Trip time for motors with protection Ex e (increased safety) shall be shorter than t_E according to IEC 60079-7 for Group IIA Class T3 (200°C).

5 TECHNICAL DOCUMENTATION AND INFORMATION

5.1 DOCUMENTS FOR PROPOSAL

The following documents and information shall be annexed to the proposal for the motor and all related equipment and accessories:

- a) Preliminary dimensional drawings, including weights;
- b) Technical catalogue;
- c) Preliminary dimensional drawing and technical information for bearings, when applicable;

- d) Data-sheet issued by PETROBRAS completely filled in with Manufacturer data;
- e) Data-sheet following template of I-LI-3010.00-5140-700-P4X-001 - ELECTRICAL EQUIPMENT DATA SHEET MODELS completely filled in, when not issued by PETROBRAS;
- f) Starting time calculation report including calculation of the relation t_a/t_{lr} , current-speed curves and torque-speed curves for motor and driven machine, printed on the same graphic, for motors 55 kW and above. Two reports shall be presented, one for rated voltage and other for 80 % of rated voltage;
- g) Temperature rise test report for motors installed in hazardous area and for motors fed from VSD or when required in Data Sheet;
- h) Permissible torque-frequency curve for motors fed from VSD;
- i) Voltage-frequency curve for motors fed from VSD (according to IEC 60034-25);
- j) Electrical and mechanical parameters, including:
 - locked-rotor, pull-up (if applicable) and breakdown torques;
 - efficiency and power factor for 100%, 75% and 50% of load;
 - locked-rotor power factor and current;
 - motor electrical model with reactances and resistances for rated speed and for locked rotor conditions;
 - heating and cooling time constants for motors rating 55 kW and above;
 - moment of inertia for motors rating 55 kW and above.
- k) Painting method;
- l) Applicable Standards, Codes and Rules;
- m) Tests List;
- n) Spare parts list, including code numbers and unit price;
- o) Mean Time to Repair (MTTR).

Note: All warning and safety instructions shall be issued in Portuguese language, or in English and Portuguese languages.

5.2 DOCUMENTS FOR APPROVAL

The following documents and information shall be submitted for PETROBRAS approval, after Supplier definition, for the motor and all related equipment and accessories:

- a) Dimensional drawings with all views, cross-sections, connections, terminals location, instruments and accessories location, forces, tolerances, weights, fixation holes, disassembling required space;
- b) Wiring diagram(s) for motor, instruments, panels, sensors and lubrication equipment, when applicable;
- c) Details of terminal boxes;
- d) Data-sheet issued by PETROBRAS completely filled in with Manufacturer data;
- e) Data-sheet following template of I-LI-3010.00-5140-700-P4X-001 - ELECTRICAL EQUIPMENT DATA SHEET MODELS completely filled in, when not issued by PETROBRAS;
- f) List of spare parts necessary for two years operation period, with code number and unit prices;
- g) List of standards applicable to design, manufacturing and testing;

- h) Drawing(s), specifications and Data Sheet for bearings, when applicable;
- i) Drawing of identification plate;
- j) Speed-torque and speed-current curves at 100% and 80 % rated voltage for motors 55kW and above;
- k) For motors above 55 kW, the manufacturer shall supply the negative sequence capability curve for the stator and rotor;
- l) Conformity certificates with valid dates (for type tests) for motors certified for installation in hazardous areas according to INMETRO *Portaria* nº 115, March 21st, 2022;
- m) Heating and cooling time constants (stator and rotor) for motors 55 kW and above;
- n) Identification plates;
- o) 3D model files;
- p) Inspection and Test Plan;
- q) Tests Procedure.

Note: All warning and safety instructions shall be issued in Portuguese language, or in English and Portuguese languages.

5.3 DOCUMENTS AFTER APPROVAL

Assembly, Installation, Operation and Maintenance manuals shall be furnished, after documentation approval, containing at least the following information:

- a) Technical specifications for the motor, all components and accessories, in accordance with the approved requirements (as built);
- b) Details regarding any spare units;
- c) Installation procedures;
- d) Storage and preservation treatment procedures;
- e) Operation procedures;
- f) Procedures for preventive and corrective maintenance of motor and all accessories, including list of necessary tools;
- g) Technical reports of all tests;
- h) Starting, operational and stopping procedures, including permissible number of starts per time, procedures before starting and procedures after normal and abnormal stopping;
- i) Lubrication procedures;
- j) Lifting procedures;
- k) Bearings and seals disassembly and assembly procedures;
- l) Rotor disassembly and assembly detailed procedures, with drawings and weights of each part, lifting drawings, support drawings to receive each disassembled part, drawings of activity sequences, lifting heights, etc.
- m) Conformity certificates with valid dates (for routine and special tests) for motors installed in hazardous areas according to INMETRO *Portaria* nº 115, March 21st, 2022;
- n) As built and certified version for all documents cited in items 5.1 and 5.2.

Note: Manuals shall comply with content requirements of NR-12 as defined in I-ET-3010.00-5140-700-P4X-001 - SPECIFICATION FOR ELECTRICAL DESIGN FOR OFFSHORE UNITS.

6 INSPECTION AND TESTS

6.1 GENERAL


- 6.1.1 The tests listed in Table 4 shall be performed. Any other test required by Classification Society shall be also carried out.
- 6.1.2 Type tests (T) shall be carried out on the first of a batch of identical motors. Type tests reports carried out on a prototype motor may be acceptable for those tests indicated in Table 4.
- 6.1.3 Routine tests (R) shall be carried out on each motor.
- 6.1.4 Special tests (S) shall be carried out on each motor.
- 6.1.5 For all tests required, including those during the manufacturing process, test procedures shall be submitted to PETROBRAS for approval. After tests have been performed test reports shall be also issued.
- 6.1.6 For tests which are required to be performed at rated frequency, the frequency of 60 Hz shall be considered.

6.2 TESTS LIST

At least the following tests shall be carried out:

Table 4 - Minimum Tests List.

Test	T	R	S	Method and Acceptance Criteria
Verification of data on name plate and visual inspection		x		IEC 60034-1 and this ET
Verification of painting (colour, thickness and adhesion)	x			DR-ENGP-I-1.15 – COLOR CODING and I-ET-3010.00-1200-956-P4X-002 - GENERAL PAINTING
Verification of degree of enclosure protection (IP) ⁽²⁾	x			IEC 60034-5
Verification of terminal boxes internal space and components (grounding and phase terminals, etc.)	x			This ET
Verification of Certification Reports for Ex motors		x		Applicable IEC and INMETRO Portaria 115/2022
Verification of Certification Reports of group motor/VSD, or motor/soft-starter for motor installed in hazardous area		x		IEC 60079-14
Measurement of insulation resistance and polarization index			x	IEEE Std 43
Measurement of winding's resistances (cold condition)		x		IEC 60034-1
Measurement of no-load current and losses at rated voltage and frequency		x		IEC 60034-1 and Motor Data Sheet
Measurement of efficiency by low uncertainty methods ⁽³⁾	x			IEC 60034-2-1 and Portaria n° 553
Measurement of power factor at rated voltage and frequency for 100%, 75% and 50% of rated load ⁽³⁾	x			Motor Data Sheet
Measurement of noise ⁽³⁾		x		IEC 60034-9 and I-ET-3010.00-1200-300-P4X-001 - NOISE AND VIBRATION CONTROL REQUIREMENTS
Measurement of locked-rotor current and torque at rated voltage and frequency ⁽³⁾	x		x ⁽¹⁾	This ET and Motor Data Sheet

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Test	T	R	S	Method and Acceptance Criteria
Measurement of pull-up and breakdown torques and their relative slips ⁽³⁾	x	X ⁽¹⁾		IEC 60034-12 and Motor Data Sheet
Measurement of shaft voltage for converter-fed motors		x		IEC 60034-25
Vibration and balance test, including lubrication system for motors with shaft heights 56 mm or higher			x	IEC 60034-14
Withstand voltage test (test of insulation to ground)		x		IEC 60034-1
Open circuit secondary induced voltage test for wound rotors		x		IEC 60034-1
Bearing insulation test, when applicable			x	Bearing Manufacturer
Direction of rotation test		x		IEC 60034-1
Overspeed test ⁽³⁾	x			IEC 60034-1
Temperature rise test at full load ⁽³⁾	x			IEC 60034-1 and IEC 60085
Temperature rise test for sleeve bearings			x	IEC 60034-1 and limits by Bearing Manufacturer
Occasional excess current test for rated power up to 315 kW ⁽³⁾	x			IEC 60034-1
Momentary excess torque test ⁽³⁾	x			IEC 60034-1
Partial discharge for converter-fed motors (power frequency PD tests)			x	IEC 60034-18-41
Partial discharge for converter-fed motors (impulse PD tests)			x	IEC 60034-18-41
Surge Comparison Test for converter-fed motors			x	ANSI/EASA AR100
Temperature rise test at full load for Ex motors ⁽²⁾	x			IEC 60079-0
Determination of explosion pressure for Ex d motors ⁽²⁾	x			IEC 60079-1
Overpressure test for Ex d motors ⁽²⁾	x			IEC 60079-1
Test of non-transmission of internal ignition for Ex d motors ⁽²⁾	x			IEC 60079-1
Determination of starting current ratio I_A/I_N and time t_E for Ex e motors ⁽²⁾	x			IEC 60079-7
Impulse ignition test for Level of Protection “eb” stator insulation systems, for Ex e motors ⁽²⁾	x			IEC 60079-7
Steady state ignition test for Levels of Protection “eb” and “ec” stator insulation systems, for Ex e motors ⁽²⁾	x			IEC 60079-7
Cage rotor test for Ex e motors ⁽²⁾	x			IEC 60079-7

- Notes:**
- 1) For motors with power equal to and above 200 kW.
 - 2) Type Test reports performed in a prototype motor may be acceptable if analysed and approved by PETROBRAS.
 - 3) For motors with rated power below 55 kW Type Test reports performed in a prototype motor may be acceptable if analysed and approved by PETROBRAS.


6.3 STRING TESTS

6.3.1 String tests shall be performed for all machines driven by motors when required in driven machine Project Documentation.

6.3.2 The following tests (and others required in Project Documentation) shall be carried out:

Table 5 - String Tests.

Test	Method and Acceptance Criteria
Measurement of noise	IEC 60034-9 and I-ET-3010.00-1200-300-P4X-001 - NOISE AND VIBRATION CONTROL REQUIREMENTS
Measurement of power factor at rated voltage and frequency for 100%, 75% and 50% of rated load.	Motor Data Sheet
Measurement of shaft voltage for converter-fed motors	IEC 60034-25

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Test	Method and Acceptance Criteria
Measurements at full load with rated voltage and frequency	Motor Data Sheet
Vibration and balance tests of package, including lubrication system	Zone B of ISO 10816-1 ⁽¹⁾
Temperature rise test of motor at full load	IEC 60034-1 and IEC 60085
Bearing temperature rise test	IEC 60034-1 and Limits by Bearing Manufacturer
Temperature rise test at full load for Ex motors	IEC 60079-0
4 hours continuous operation at full load ⁽²⁾	IEC 60034-1 and limits by IEC 60085
Performance test for motors driving fire-fighting pumps	NFPA 20

Notes: 1) If driven machine manufacturer requires a different limit for vibration, the lower limit shall prevail.

7 ANNEX I – ABBREVIATIONS AND ACRONYMS

DOL	Direct On-line
EPL	Equipment Protection Level
ET	Technical Specification
FPSO	Floating, Production, Storage and Offloading Unit
FSO	Floating, Storage and Offloading Unit
IEC	International Electrotechnical Commission
IEEE	Institute of Electrotechnical and Electronic Engineers
I_r	Locked rotor current
INMETRO	Instituto Nacional de Metrologia Normalização e Qualidade Industrial
I_r	Rated current
IVIC	Impulse Voltage Insulation Class
NEMA	National Electrical Manufacturers Association
PC	Material Purchase Order
PD	Partial Discharge
RM	Material Requisition
RMS	Root Mean Square
R	Routine Test
RTD	Resistance Temperature Detector
SPDT	Single Pole Double Through
S	Special Test
t_a	Acceleration time
T_b	Breakdown torque
t_E	Time, in seconds, taken for an A.C. motor or stator winding, when carrying the initial starting current I_A , to be heated up to the limiting temperature from the temperature reached in rated service at the maximum ambient temperature (based on IEC 60079-7)
TEFC	Totally Enclosed Fan Cooled
T_l	Locked rotor torque
t_{lr}	Permissible locked rotor time
T_N	Rated torque at rated speed and rated output power
T	Type Test
T_u	Pull-up torque
VPI	Vacuum Pressure Impregnation
VSD	Variable Speed Drive